

# Machine Learning with Graphs: Spectral Graph Theory 1/3 - Intro, Laplacian

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Spectral Graph Theory (SGT) provides elegant connections between graphs and matrices—especially the so-called graph Laplacian. While most relevant graph problems are NP-hard, a few of them can be approximated as eigenvector/eigenvalue problems, which are solvable in poly-time. Here, we will introduce the Laplacian matrix and show how we can use its spectrum to solve machine learning problems, such as graph partitioning.

## Linear algebra

Spectral graph theory relies on a few fundamental concepts and theorems from Linear Algebra. If you need a refresher on the subject, Gilbert Strang's books [5, 4] are good references.

We say that  $(\lambda, \mathbf{x})$  is an *eigenvalue-eigenvector* pair for a matrix  $M$  if:

$$M\mathbf{x} = \lambda\mathbf{x}$$

Eigenvalues can also be defined as roots of a matrix polynomial:

$$\det(\lambda I - M)$$

We will focus on the case where  $M$  is symmetric. Thus, we can use the *spectral theorem* to show that  $M$  has real eigenvalues and *orthonormal* eigenvectors.

**Theorem 1** (*The spectral theorem*) *A real symmetric matrix  $M \in \mathbb{R}^{n \times n}$  has real eigenvalues  $\lambda_1, \dots, \lambda_n$  and orthonormal eigenvectors  $\mathbf{x}_1, \dots, \mathbf{x}_n$ .*

The *quadratic form* of a square matrix  $M$  is the scalar  $\mathbf{x}^T M \mathbf{x} = \sum_{i,j} M_{i,j} \mathbf{x}_i \mathbf{x}_j$ . We can use the quadratic form to define the *Rayleigh–Ritz quotient* of  $M$ ,  $\mathbf{x}^T M \mathbf{x} / \mathbf{x}^T \mathbf{x}$ . The *Courant-Fischer theorem* applies the Rayleigh-Ritz quotient of  $M$  to define eigenvalues as the solution of optimization problems.

**Theorem 2** (*Courant-Fischer theorem*) *The eigenvalues  $\lambda_1, \dots, \lambda_n$  of a symmetric matrix  $M$  are such that:*

$$\lambda_k = \max_{\substack{S \subseteq \mathbb{R}^n \\ \dim(S)=k}} \min_{\substack{\mathbf{x} \in S \\ \mathbf{x} \neq 0}} \frac{\mathbf{x}^T M \mathbf{x}}{\mathbf{x}^T \mathbf{x}} = \min_{\substack{T \subseteq \mathbb{R}^n \\ \dim(T)=n-k+1}} \max_{\substack{\mathbf{x} \in T \\ \mathbf{x} \neq 0}} \frac{\mathbf{x}^T M \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$$

where  $S$  and  $T$  are subspaces and  $\dim(S)$  is the dimension of  $S$ .

The following definitions for  $\lambda_1, \lambda_2, \lambda_3, \dots$  follow from Courant-Fischer:

$$\begin{aligned} \lambda_1 &= \min_{\mathbf{x} \neq 0} \frac{\mathbf{x}^T M \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \\ \lambda_2 &= \min_{\substack{\mathbf{x} \neq 0 \\ \mathbf{x} \perp \mathbf{x}_1}} \frac{\mathbf{x}^T M \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \\ \lambda_3 &= \min_{\substack{\mathbf{x} \neq 0 \\ \mathbf{x} \perp \{\mathbf{x}_1, \mathbf{x}_2\}}} \frac{\mathbf{x}^T M \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \end{aligned}$$

Notice that, for orthonormal eigenvectors, the denominator  $\mathbf{x}^T \mathbf{x} = 1$ .

## The Laplacian matrix

We will assume that  $G$  is undirected and unweighted. However, everything discussed here can be easily generalized to the case of weighted graphs.

The Laplacian can be defined in terms of the *adjacency* and *degree* matrices. The adjacency matrix  $A \in \mathbb{R}^{n \times n}$  of a graph  $G = (V, E)$  is defined as:

$$A_{ij} = \begin{cases} 1 & \text{if } (v_i, v_j) \in E \\ 0 & \text{otherwise} \end{cases}$$

And the degree matrix of  $G$  is defined as:

$$D_{ij} = \begin{cases} \deg(v_i) & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

The Laplacian  $L \in \mathbb{R}^{n \times n}$  of  $G$  is the difference between the degree and adjacency matrices:

$$L = D - A$$

The first interesting property of the Laplacian is that its quadratic form is a measure of the “smoothness” of  $\mathbf{x}$  in  $G$ :

$$\mathbf{x}^T L \mathbf{x} = \sum_{(v_i, v_j) \in E} (x_i - x_j)^2$$

It follows that  $L$  is positive semi-definite (PSD), since  $\mathbf{x}^T L \mathbf{x} \geq 0$ . Moreover, we can use the Courant-Fischer theorem to show that its first eigenvalue  $\lambda_1 = 0$

with eigenvector  $\mathbf{1}_n/\sqrt{n}$  ( $\mathbf{x}^T L \mathbf{x} = 0$ ). Using a similar argument, we can show that the second eigenvalue  $\lambda_2 = 0$  iff  $G$  is disconnected—we can again find a vector  $\mathbf{x}$  such that  $\mathbf{x}^T L \mathbf{x} = 0$  and  $\mathbf{x} \perp \mathbf{1}_n/\sqrt{n}$ .

So far, our understanding of the spectrum of the Laplacian is limited to  $(\lambda_1, \mathbf{x}_1)$  and, if the graph is disconnected,  $(\lambda_2, \mathbf{x}_2)$ . But what can we say about  $\lambda_2, \dots, \lambda_n$  and  $\mathbf{x}_1, \dots, \mathbf{x}_n$  in general? We can gain some insights by looking at specific graphs.

A clique (or complete graph) with  $n$  vertices has Laplacian  $L = nI - \mathbf{1}_{n \times n} = nI - \mathbf{1}_n \mathbf{1}_n^T$ , where  $I$  is the identity matrix. By definition,  $nI \mathbf{x} = n \mathbf{x}$  for any  $\mathbf{x}$ . Moreover, eigenvectors of  $\mathbf{1}_n \mathbf{1}_n^T$  are such that  $\mathbf{1}_n^T \sum_i \mathbf{x}[i] = \lambda \mathbf{x}$ . We know that  $\mathbf{x}_n = \mathbf{1}_n$  is an eigenvector with eigenvalue  $\lambda_n = n$ . All other eigenvectors  $\mathbf{x}_1, \dots, \mathbf{x}_{n-1}$  must be orthogonal to  $\mathbf{1}_n$  ( $\sum_i \mathbf{x}[i] = 0$ ) and thus their associated eigenvalue must be  $\lambda_1 = \dots = \lambda_{n-1} = 0$ . Because these eigenvectors are also eigenvectors of  $nI$ , they are eigenvectors of  $L$  with eigenvalues  $\lambda'_1 = n - n = 0$  and  $\lambda_2 = \dots = \lambda_n = n - 0 = n$ .

## References

- [1] Fan RK Chung and Fan Chung Graham. *Spectral graph theory*. American Mathematical Soc., 1997.
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- [3] Daniel Spielman. Spectral graph theory. *Combinatorial scientific computing*, 2012.
- [4] Gilbert Strang. *Linear algebra and learning from data*. Wellesley-Cambridge Press, 2019.
- [5] Gilbert Strang. Introduction to linear algebra. 2021.