# CS6501/4501: Vision and Language Video and Language

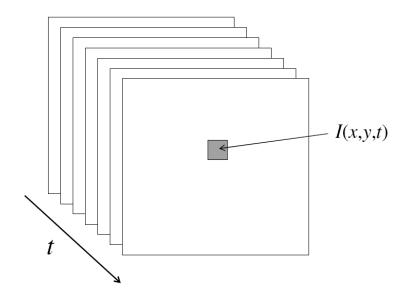


# Today's Class

- Video:
  - Optical flow
  - Two-Stream Networks
  - CNN + LSTM
  - CNN + Temporal Pooling
  - 3D CNNs

# From images to videos

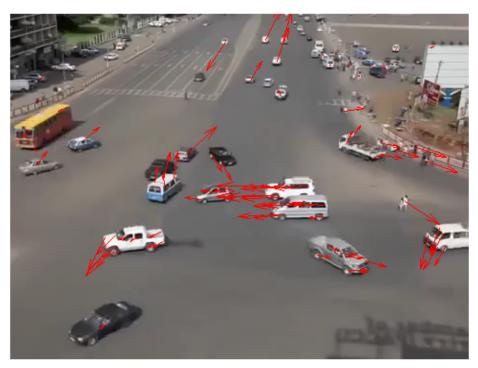
- A video is a sequence of frames captured over time
- Now our image data is a function of space (x, y) and time (t)



# Why is motion useful?



# Why is motion useful?

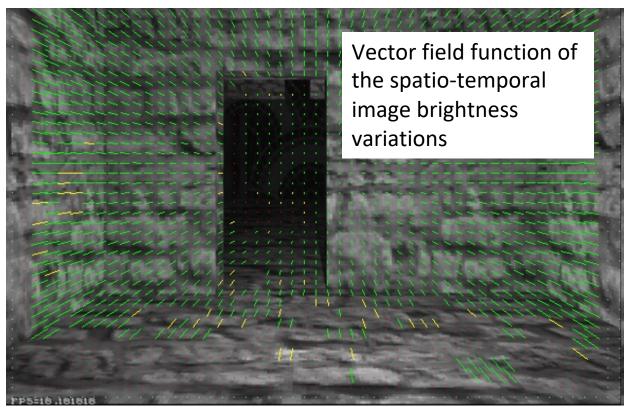


# Optical flow

- Definition: optical flow is the *apparent* motion of brightness patterns in the image
- Note: apparent motion can be caused by lighting changes without any actual motion
  - Think of a uniform rotating sphere under fixed lighting vs. a stationary sphere under moving illumination

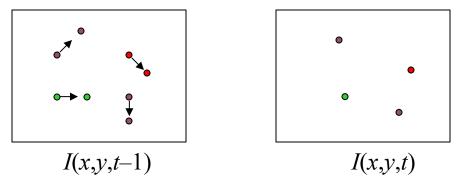
**GOAL:** Recover image motion at each pixel from optical flow

## Optical flow



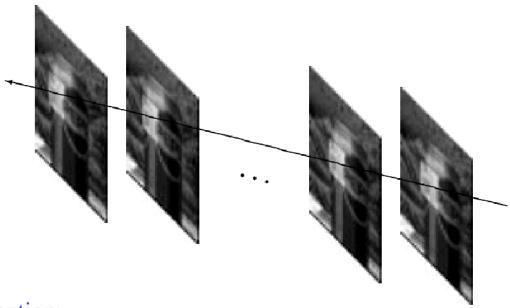
Picture courtesy of Selim Temizer - Learning and Intelligent Systems (LIS) Group, MIT

# Estimating optical flow



- Given two subsequent frames, estimate the apparent motion field u(x,y), v(x,y) between them
- Key assumptions
  - **Brightness constancy:** projection of the same point looks the same in every frame
  - Small motion: points do not move very far
  - Spatial coherence: points move like their neighbors

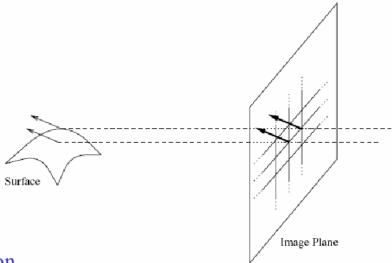
## Key Assumptions: small motions



Assumption:

The image motion of a surface patch changes gradually over time.

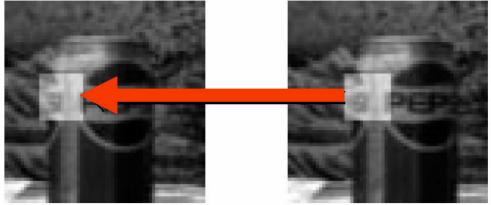
## Key Assumptions: spatial coherence



#### Assumption

- \* Neighboring points in the scene typically belong to the same surface and hence typically have similar motions.
- \* Since they also project to nearby points in the image, we expect spatial coherence in image flow.

Key Assumptions: brightness Constancy



#### Assumption

Image measurements (e.g. brightness) in a small region remain the same although their location may change.

$$I(x+u, y+v, t+1) = I(x, y, t)$$

(assumption)

#### The brightness constancy constraint

displacement 
$$= (u, v)$$

$$I(x,y,t-1)$$

$$I(x,y,t)$$

• Brightness Constancy Equation:

$$I(x, y, t-1) = I(x + u(x, y), y + v(x, y), t)$$

Linearizing the right side using Taylor expansion:

$$\begin{split} &I(x+u,y+v,t) \approx I(x,y,t-1) + \begin{matrix} I_x \\ I_x \end{matrix} u(x,y) + \begin{matrix} I_y \cdot v(x,y) + \begin{matrix} I_t \\ I_t \end{matrix} \\ & I(x+u,y+v,t) - I(x,y,t-1) = \begin{matrix} I_x \cdot u(x,y) + \begin{matrix} I_y \cdot v(x,y) + \begin{matrix} I_t \\ I_t \end{matrix} \\ & \text{Hence,} \quad \begin{matrix} I_x \cdot u + \begin{matrix} I_y \cdot v + \begin{matrix} I_t \\ I_t \end{matrix} \approx 0 \quad \Rightarrow \nabla I \cdot \begin{bmatrix} u & v \end{bmatrix}^T + \begin{matrix} I_t \\ I_t \end{matrix} = 0 \end{split}$$

Source: Silvio Savarese

#### The brightness constancy constraint

(x,y)displacement = (u,v)

B. Lucas and T. Kanade. An iterative image registration technique with an application to stereo vision. In *Proceedings of the International Joint Conference on Artificial Intelligence*, pp. 674–679, 1981.

 $I(x+u,y+v,t) - I(x,y,t-1) = I_x \cdot u(x,y) + I_y \cdot v(x,y) + I_t$ Hence,  $I_x \cdot u + I_y \cdot v + I_t \approx 0 \quad \Rightarrow \nabla I \cdot \begin{bmatrix} u & v \end{bmatrix}^T + I_t = 0$ 

Source: Silvio Savarese

Recommended Paper to Read:

#### **Quo Vadis, Action Recognition? A New Model and the Kinetics Dataset**

João Carreira<sup>†</sup>

Andrew Zisserman<sup>†,\*</sup>

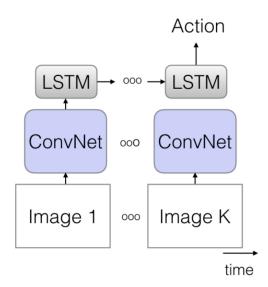
joaoluis@google.com

zisserman@google.com

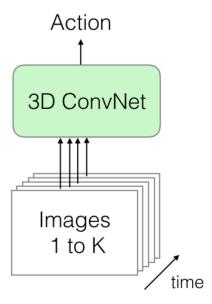
†DeepMind

\*Department of Engineering Science, University of Oxford

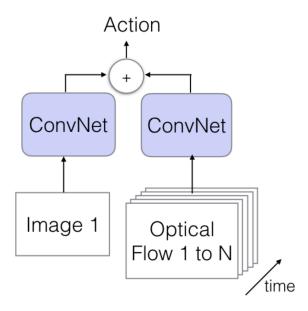
#### CNN + LSTM over sequence of frames



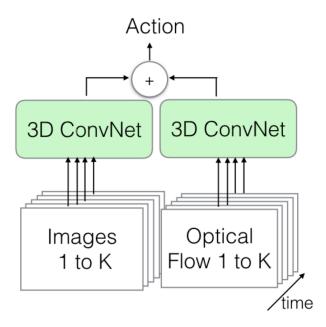
#### 3D CNN of consecutive frames across time



Two Stream CNN: Images + Flow Map



Two Stream 3D CNN: Images + Flow Map



### UCF-101 Action Dataset



#### Results on UCF101 actions

	UCF-101						
Architecture	RGB	Flow	RGB + Flow				
(a) LSTM	81.0	_	_				
(b) 3D-ConvNet	51.6	_	_				
(c) Two-Stream	83.6	85.6	91.2				
(d) 3D-Fused	83.2	85.8	89.3				
(e) Two-Stream I3D	84.5	90.6	93.4				

#### **Movie Trailers**

#### Moviescope: Large-scale Analysis of Movies using Multiple Modalities

Paola Cascante-Bonilla<sup>1\*</sup> Kalpathy Sitaraman<sup>2†\*</sup> Mengjia Luo<sup>1</sup> Vicente Ordonez<sup>1</sup>

<sup>1</sup>University of Virginia, <sup>2</sup>Microsoft

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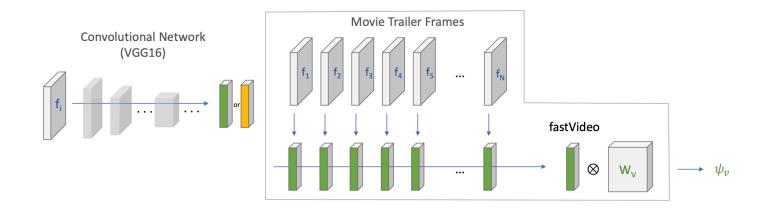


## **Movie Trailers**

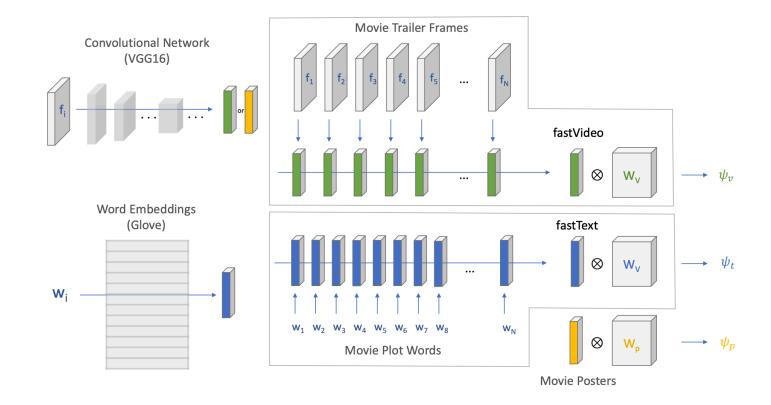


- Movie Trailers
- Movie Plots
- Movie Posters
- Movie Metadata

# CNN + Temporal Pooling



# CNN + Temporal Pooling



# Results

Table 3. Mean Average Precision (mAP) Scores for movie genre prediction.

	action	anim	bio	com	crime	drama	fam	fant	horr	myst	rom	scifi	thrlr	mAP	$\mu AP$	sAP
% of training samples	8.70	1.84	2.22	14.17	10.56	19.63	4.14	6.97	4.29	3.79	8.36	4.66	10.69	-	-	-
Baseline accuracy	22.1	4.3	6.2	39.3	18.6	53.6	10.8	17.0	10.5	10.9	22.1	13.5	25.8	19.6	13.7	21.0
Video (V)																
C3D [37]	63.8	91.3	16.2	82.3	45.1	71.6	65.3	54.8	50.8	28.2	38.3	21.8	64.8	53.4	57.9	68.8
I3D [5]	37.2	51.8	9.2	72.6	33.9	67.6	43.6	39.0	22.8	21.3	34.3	22.6	48.3	38.8	50.5	65.6
LSTM	47.5	86.8	12.0	79.2	33.0	72.0	64.5	54.4	22.7	24.7	40.4	36.5	54.8	48.4	59.6	70.5
Bidirectional LSTM	49.9	86.3	8.2	77.6	29.9	70.8	65.4	55.3	22.3	21.7	41.6	35.9	51.2	47.4	58.2	69.9
fastVideo	61.4	94.8	23.9	81.5	41.7	77.0	67.0	62.6	36.1	30.4	48.4	48.2	62.0	56.5	64.9	75.6
fastVideo + TempConv	64.7	95.7	21.2	83.5	49.1	78.9	68.6	68.9	42.7	29.2	46.8	51.0	64.8	58.9	65.9	<b>76.3</b>
Audio (A)																
CRNN	56.7	48.0	11.2	86.2	40.0	79.0	49.6	44.7	37.6	22.7	43.0	27.0	56.3	46.3	61.4	72.3
Poster (P)																
VGG16	48.6	60.0	12.1	73.4	33.4	69.8	47.2	41.3	37.0	22.3	38.1	33.9	46.3	43.3	51.9	66.5
Text (T)																
Conv1D	62.5	34.4	24.7	64.8	54.3	73.8	50.3	64.6	50.4	31.5	43.2	70.6	61.5	52.8	57.8	70.4
LSTM	64.8	44.5	25.6	70.1	63.4	78.0	63.3	70.8	63.2	32.6	47.1	75.2	66.5	58.9	63.8	73.8
Bidirectional LSTM	63.7	42.5	31.2	69.3	58.1	76.7	57.9	66.4	61.3	30.7	52.3	76.2	63.2	57.7	63.2	73.5
fastText	72.0	50.7	40.6	81.1	68.7	82.3	69.2	68.8	78.3	47.8	60.3	74.4	72.9	66.7	72.5	81.4
fastText w/ Glove [20]	72.2	51.6	45.2	81.2	69.1	82.3	70.8	68.9	78.8	49.7	61.1	75.2	73.3	67.7	<b>72.8</b>	81.7
Metadata (M)																
XGBoost	61.5	76.8	35.4	74.8	36.7	82.7	83.7	53.7	62.3	22.8	31.4	33.4	50.9	54.3	62.9	73.7
RandomForest	59.3	73.7	33.3	74.9	40.6	82.7	83.2	58.8	62.7	25.4	35.4	37.9	55.0	55.6	63.9	<b>73.7</b>
Score Fusion																
Video-Audio (VA)	69.0	90.8	26.1	88.6	49.0	82.6	74.8	63.8	49.0	34.4	49.8	51.1	70.8	61.5	70.3	78.8
Vid-Aud-Poster (VAP)	68.8	92.5	27.4	88.5	48.9	82.6	74.8	63.7	49.5	34.3	50.1	50.3	70.7	61.7	70.4	78.8
Vid-Aud-Post-Text (VAPT)	73.3	95.2	29.9	91.0	61.2	85.0	77.2	69.0	68.9	38.8	51.8	61.6	74.1	67.5	74.9	82.3
Vid-Aud-Post-Text-Metad (VAPTM)	75.5	88.8	36.6	91.5	60.6	86.8	87.0	70.5	74.6	39.7	49.7	59.4	71.3	68.6	75.3	82.5

## Results

Table 4. Mean Average Precision Scores on UCF101.

	mAP
'Slow Fusion' spatio-temporal ConvNet [16]	65.4
LSTM composite model (only RGB) [34]	75.8
C3D (fc6) [37]	76.4
iDT+C3D (fc6) [37]	86.7
Two-stream model [28]	88.0
Two-Stream I3D [5]	98.0
fastVideo - 16 Frames	79.2
fastVideo - 200 Frames	79.4
fastVideo - 49 Frames	81.1

# Other Video and Language

- Youtube videos with titles
  - http://aliensunmin.github.io/project/video-language/index.html#VTW
- YouCook2 Dataset
  - http://youcook2.eecs.umich.edu/
- MSRVTT: Microsoft Video and Text Dataset
  - <a href="https://www.microsoft.com/en-us/research/publication/msr-vtt-a-large-video-description-dataset-for-bridging-video-and-language/">https://www.microsoft.com/en-us/research/publication/msr-vtt-a-large-video-description-dataset-for-bridging-video-and-language/</a>

# Questions?